Mathematics of Deep Learning Reading Group. April 28th, 2022

#### **Developments in Inference with Linearised Neural Networks**

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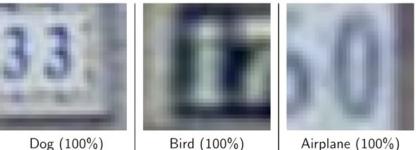
- 1. Preliminaries: probabilistic inference in neural networks and the linearised Laplace method
- 2. Paper overview: "Improving predictions of Bayesian neural networks via local linearization"
- 3. Informal discussion

# Preliminaries

## Preliminaries: open problems in deep learning

#### **Overconfidence**

Training on CIFAR10 - Test on SVHN



Dog (100%)

Airplane (100%)

10.0 7.5 5.0 2.5 0.0 -2.5

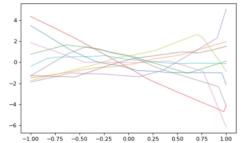
https://vitalab.github.io/article/2019/07/11/overconfident.html

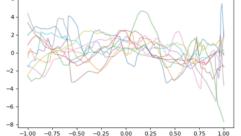
#### **Model Selection**

#### 1 Hidden Layer

5 Hidden Layer

#### 20 Hidden Layer





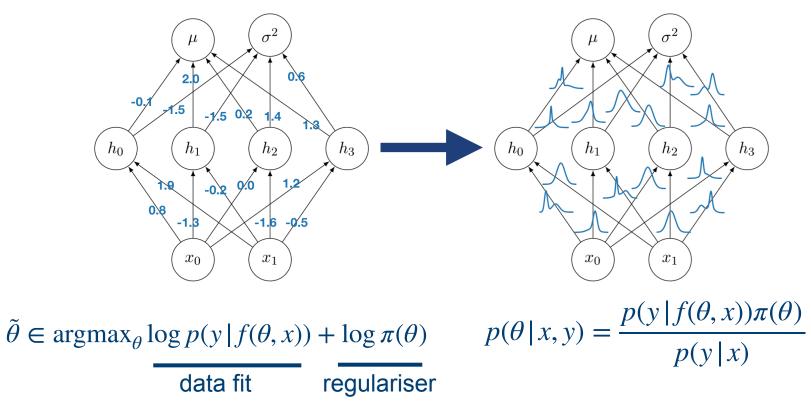


0.25 0.50 0.75 1.00

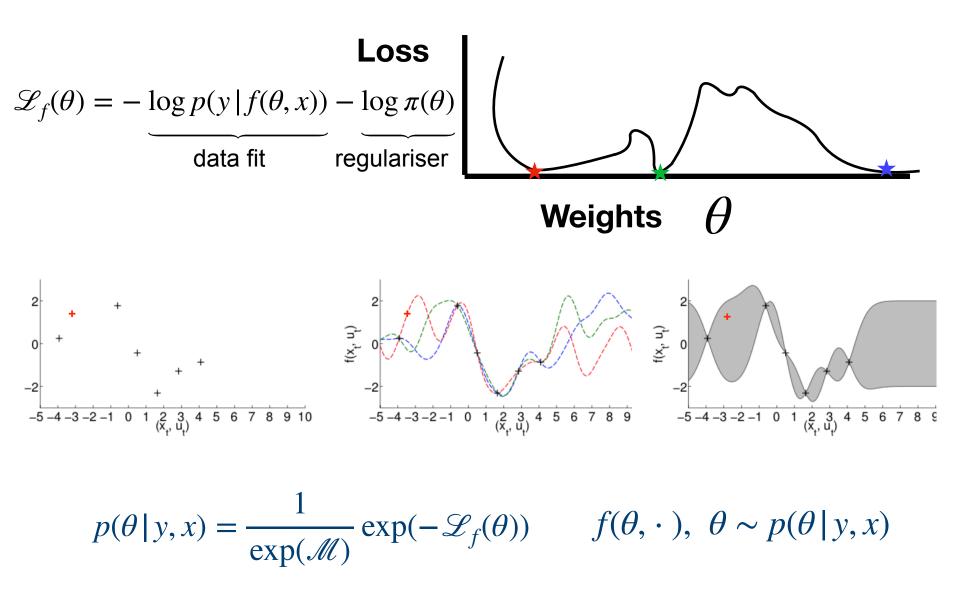
-1.00 -0.75 -0.50 -0.25 0.00

## Preliminaries: probabilistic inference in NNs

- **1.** Place a prior distribution  $\pi(\theta)$  over NN parameters.
- **2.** Define some likelihood function  $p(y | f(\theta, x))$  to characterise the agreement of the NN function  $f(\theta, \cdot)$  with the observations (y, x)
- 3. Update the weight distribution using Bayes' rule



## **Preliminaries: uncertainty estimation**



$$\mathscr{L}_{f}(\theta) = -\log p(y | f(\theta, x)) - \log \pi(\theta) \quad p(\theta | y, x) = \frac{1}{\exp(\mathscr{M})} \exp(-\mathscr{L}_{f}(\theta))$$

1

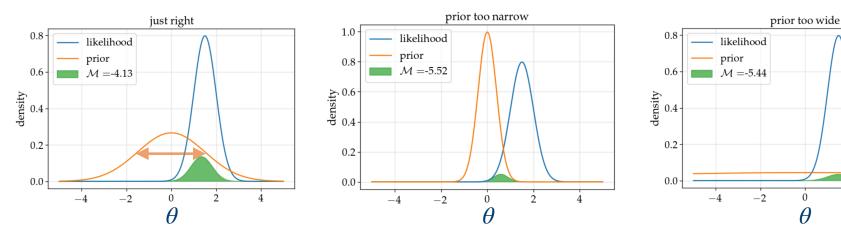
2

0

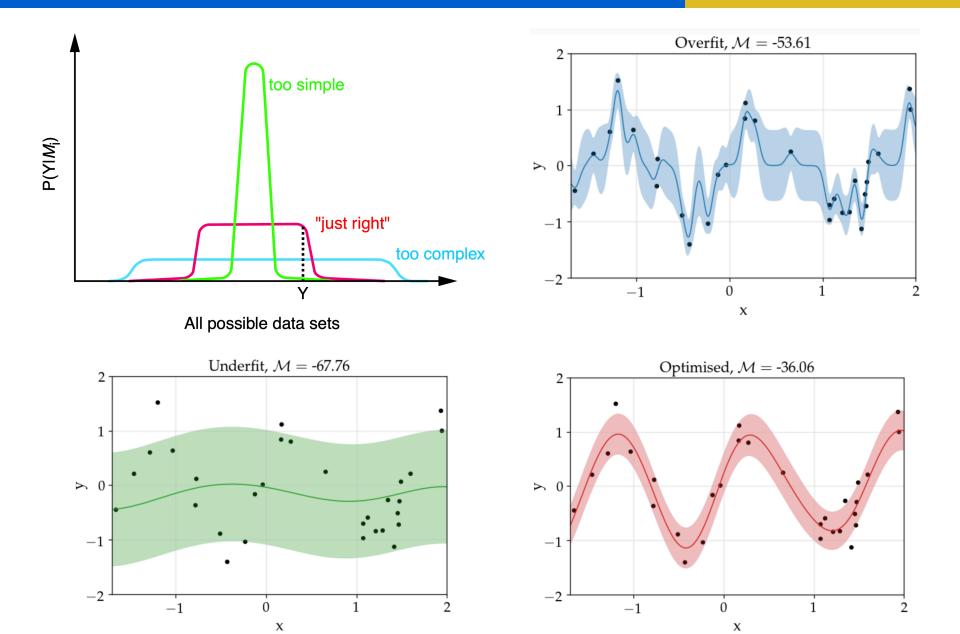
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The normalisation constant,  $\mathcal{M}$ , is the *marginal likelihood*, or *model evidence*. It is the probability that our observations where generated by our prior. It provides an objective for hyperparameter selection without the need for validation data.

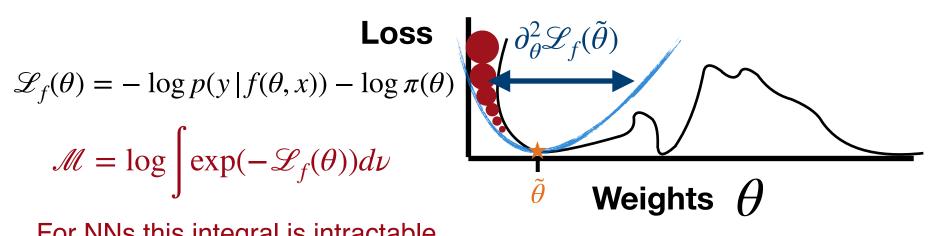
$$\mathcal{M} = \log p(y|x) = \log \int p(y|f(\theta, x))d\pi = \log \int \exp(-\mathscr{L}_f(\theta))d\nu$$



## **Preliminaries: automatic Occam's razor**



## Preliminaries: the Laplace approximation



For NNs this integral is intractable

Idea: Find a mode of  $\mathscr{L}_f$ :  $\tilde{\theta}$  and perform 2-order Taylor expansion  $\mathscr{G}_{f}(\theta) = \mathscr{L}_{f}(\tilde{\theta}) + ||\theta - \tilde{\theta}||^{2}_{\partial^{2}_{\theta}\mathscr{L}_{f}(\tilde{\theta})}$ 

By inspection,  $\exp(-\mathscr{G}_{f,\tilde{\theta}}(\theta))$  is proportional to  $\mathcal{N}(\tilde{\theta}, (\partial_{\theta}^2 \mathscr{L}_f(\tilde{\theta}))^{-1})$  where  $\partial_{\theta}^{2} \mathscr{L}_{f}(\tilde{\theta})) = \partial_{\theta}^{2} \log p(y | f(\tilde{\theta}, x)) + \partial_{\theta}^{2} \log \pi(\tilde{\theta}) \qquad \pi(\theta) \to \mathcal{N}(\theta; 0, \Lambda^{-1})$ 

**Issue:** A lot of mass falls in low density region, leading to bad predictions

#### PAPER DISCUSSION:

### IMPROVING PREDICTIONS OF BAYESIAN NEURAL NETWORKS VIA LOCAL LINEARIZATION