

Linearised Laplace Inference in Networks with Normalisation Layers and the Neural g-Prior

Javier Antorán (ja666@cam.ac.uk), James Allingham, Dave Janz, Erik Daxberger, Eric Nalisnick, José Miguel Hernández-Lobato

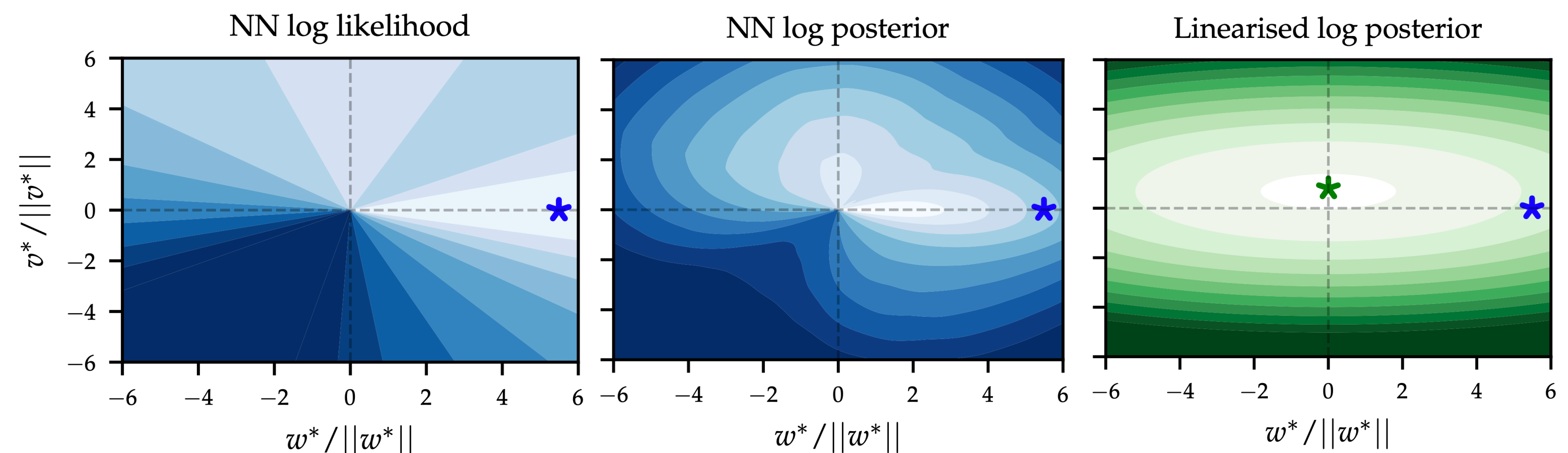
- Normalisation layers break the Laplace model evidence for model selection.
- The Jacobian of a NN has both very large and very small entries, complicating prior choice.

Normalisation Layers

- SGD can not find a mode of NN posterior or linear model posterior biasing model evidence estimates

➔ Use the mode of the linearised model: v^*

$$-\frac{1}{2} \left[\underbrace{\|w^*\|_{\Lambda}}_{\|v^*\|_{\Lambda}} + \log \det \left(\frac{H + \Lambda}{\Lambda} \right) \right] + C$$



- ★ Linearisation point found with SGD w^* — not a mode of any posterior
- ★ Mode of linearised model posterior v^* is well defined

g-Prior for Heterogeneous Jacobian Features

- Isotropic priors leave some weights underspecified while overly constraining others

➔ The 'scale invariant' g-prior induces the same posterior as scale-normalising our Jacobian features.

$$p(w) = \mathcal{N}(w; 0, g \cdot \text{diag}(\mathcal{J})^{-1})$$

